ECE 641 Advanced Topics in Supervisory Control for Discrete Event Systems

Lecture 4

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PhD Course in Electronic and Communication Engineering Credits (3/0/3) Course webpage: http://ece641.cankaya.edu.tr/

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Algorithm: Basics

Algorithm Definition

- A computable set of steps to achieve a desired result
- Precisely specified using an appropriate mathematical formalism (such as a programming language)

Efficiency of an Algorithm

Less consumption of computing resources (execution time (CPU cycles), memory)

 \Rightarrow We will focus on time efficiency

Comparison of Algorithms

Question: Assume two algorithms that accomplish the same task
 ⇒ Which one is better?

Algorithm: Example

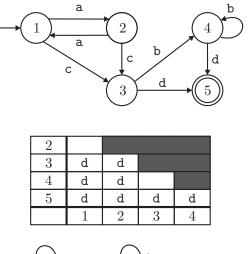
Algorithm

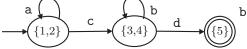
- Initialize: $q_1 = X_M$ and $q_2 = X X_m$
- Formulate table with all state pairs
- Mark all pairs with one marked and one unmarked state as distinguishable
- Mark all pairs with different outgoing transitions as distinguishable
- Mark pairs that lead to distinguishable states with the same event as distinguishable
- Repeat the previous step until all state pairs are investigated

 \Rightarrow Combine states that are indistinguishable

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Automata Graph





Algorithm: Example

State Minimization

Algorithm: Analysis

Resources

- We want to predict the resources that the algorithm requires
- Resources: Memory, processor, other hardware but MOSTLY TIME

General Notions

- Run time: Time until an algorithm produces a result
 ⇒ Run time of a given algorithm generally grows by the size of the input
- Denote size as *n*: number of items to be processed, number of bits to represent the relevant quantities, number of states, etc.
- Growth rate: How quickly the time of an algorithm grows as a function of *n*

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Algorithm: Type of Analysis

Worst Case Analysis

- Largest possible running time of algorithm on input of a given size.
- Provides an upper bound on running time
- \Rightarrow Absolute guarantee for the longest run-time for any input

Best Case Analysis

- Provides a lower bound on run-time
- Input is the one for which the algorithm runs the fastest

Average Case Analysis

- Obtain bound on run-time of algorithm on random input as a function of input size
- Hard (or impossible) to accurately model real instances by random distributions (Algorithm tuned for a certain distribution may perform poorly on other inputs)

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Algorithm. Jequential Jearen	Algorithm:	Sequential	Search
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<u>Illustration</u>

Gap 2

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Algorithm: Binary Search

<u>Illustration</u>

Algorithm: Discussion

Illustration

Gap 4

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Algorithm: Conclusions

Facts

- Run-time depends on the input size *n*
- Usually run-time is fixed for a certain n
- Different algorithms might have different run-times
- Some algorithms might be better for some inputs and worse for others
- Exact run-time depends on the algorithm but also on the processor where it runs

General Analysis

- We will look at the trend in run-time versus input size rather than exact time
- \Rightarrow Computational Complexity

Computational Complexity: Basics

Task

- Compares growth of two functions
- Independent of constant multipliers and lower-order effects

Metrics

- Big-O Notation: $O(\bullet)$
- Big-Omega Notation: $\Omega(\bullet)$
- Big-Theta Notation: $\Theta(\bullet)$

Properties

- Allow us to evaluate algorithms
- Has precise mathematical definition
- Used in a sense to put algorithms into families
- May often be determined by inspection of an algorithm

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Computational Complexity: Big-O Notation

Definition

Function f(n) is denoted as O(g(n)) for a function g(n) if there exists a constant K and some value n_0 such that for all $n \ge n_0$

$$f(n) \leq K \cdot g(n).$$

This means, as $n \to \infty$, f(n) is upper-bounded by $K \cdot g(n)$.

Useful Choices for g(n)

- $\log n$ (recall that $\log_a n$) = $k \cdot \log_b n$ for any $a, b \in \mathbb{R}$)
- n^k for $k \in \mathbb{N}_0$ (polynomial)
- k^n for some $k \in \mathbb{R}$ (exponential)

Properties

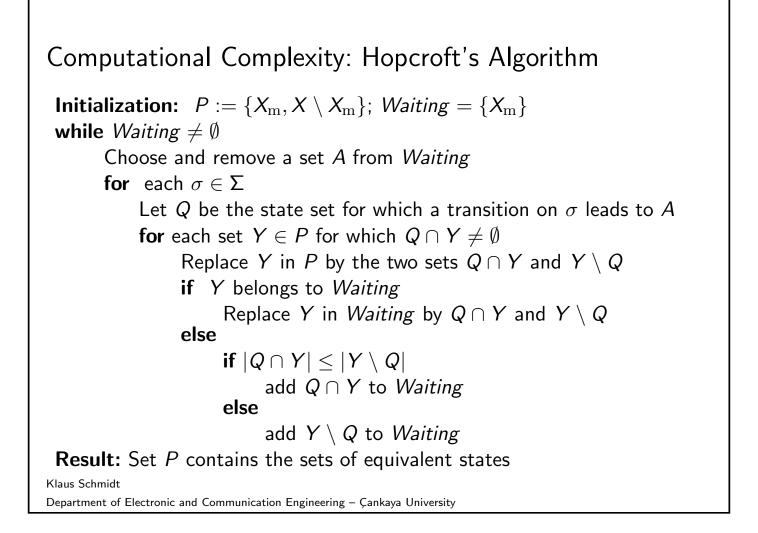
- Big-O-Notation establishes the worst-case performance
- Helps compare and see which algorithm has better performance

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State Minimization



Computational Complexity: Big-O Notation

State Minimization

Computational Complexity: Big-Omega/Theta Notation

Definition

Function f(n) is $\Omega(g(n))$ if there exists a constant K and some n_0 such that for all $n \ge n_0$ $K \cdot g(n) < f(n)$.

That is, as $n \to \infty$, f(n) is lower-bounded by $K \cdot g(n)$.

Definition

Function f(n) is $\Theta(g(n))$ if there exist constants K_1 and K_2 and some n_0 such that for all $n \ge n_0$

$$K_1 \cdot g(n) \leq f(n) \leq K_2 \cdot g(n).$$

That is, as $n \to \infty$, f(n) is upper and lower bounded by some constants times g(n).

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Computational Complexity: Big-Omega/Theta Notatioin

Illustration

Computational Complexity: Common Asymptotic Bounds

Examples

- Polynomials: a₀ + a₁ n + · · · + a_d n^d is θ(n^d) if a_d > 0
 ⇒ Polynomial time: run-time is O(n^d) for some constant d independent of the input size n
- Logarithms: $O(\log_a n) = O(\log_b n)$ for any constants a, b > 0
- Logarithm grows slower than every polynomial \Rightarrow for each d > 0, log $n = O(n^d)$
- Exponential time: run-time is $O(k^n)$ for some constant k
- Every exponential grows faster than every polynomial \Rightarrow For every k > 1 and every d > 0, $n^d = O(k^n)$

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Computational Complexity: Examples

Synchronous Composition

Gap 9

Natural Projection

Gap 10

Diagnosability