

ECE 641  
Advanced Topics in Supervisory Control for  
Discrete Event Systems  
Lecture 10

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PhD Course in Electronic and Communication Engineering  
Credits (3/0/3)

Course webpage: <http://ece641.cankaya.edu.tr/>

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## Petri Nets: Basics

### Historical Perspective

- Petri nets were developed in the early 1960s by C.A. Petri in his Ph.D. dissertation

C.A. Petri. Kommunikation mit Automaten. PhD thesis, Institut für instrumentelle Mathematik, Bonn, 1962.

### Usage of Petri Nets

- Modeling concurrent, distributed, asynchronous behavior in a discrete system
- Many families of Petri Nets for managing continuous/hybrid systems
- Timed systems
- High-level information or tasks of a system
- Variable parameter systems

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# Petri Nets: Definition

## Petri Net

- Four tuple  $N = (P, T, A, W)$
- $P$  is a finite set of places
- $T$  is a finite set of transitions
- $A \subseteq (P \times T) \cup (T \times P)$  is a finite set of arcs
- $W : A \rightarrow \mathbb{N}$  is a weighting function
- $P \cap T = \emptyset$  and  $P \cup T \neq \emptyset$

## Graphical Representation

- Places: circles
- Transitions: boxes
- Arcs: arrows  
⇒ Bipartite graph

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# Petri Nets: Definition

## Example

Gap 1

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## Petri Nets: Pre- and Post Sets

### Pre-Set $\bullet x$

- Let  $x \in P \cup T$ . Then  $\bullet x = \{y \in P \cup T \mid (y, x) \in A\}$   
 $\Rightarrow$  All predecessor nodes (places or transitions) of  $x$

### Post-Set $x^\bullet$

- Let  $x \in P \cup T$ . Then  $x^\bullet = \{y \in P \cup T \mid (x, y) \in A\}$   
 $\Rightarrow$  All successor nodes (places or transitions) of  $x$

### Example

Gap 2

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## Petri Nets: Marked Petri Net

### Definition

- Pair  $(N, m)$
- $N = (P, T, A, W)$  is a Petri Net
- $m : P \rightarrow \mathbb{N}$  is an initial marking
- Notation for  $p \in P$ :  $m[p]$  is marking of place  $p$

### Petri Net Dynamics: Transition Firing

- $t \in T$  is enabled at  $m$  iff for all  $p \in \bullet t$ :  $m[p] \geq W(p, t)$
- $t \in T$  can fire at  $m$  iff  $t$  is enabled at  $m$
- Firing of  $t$  leads to the new marking  $m'$  for each  $p \in P$  with

$$m'[p] = \begin{cases} m[p] - W(p, t) & \text{if } t \in \bullet p \\ m[p] + W(p, t) & \text{if } t \in p^\bullet \\ m[p] & \text{otherwise} \end{cases}$$

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## Petri Nets: Marked Petri Net

### Example

Gap 3

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## Petri Nets: Incidence Matrix and State Equation

### Pre- and Post Matrices

- $\forall p \in P$  and  $t \in T$ : if  $(p, t) \in A$ , then  $Pre[p, t] = W(p, t)$ , else  $Pre[p, t] = 0$
- $\forall p \in P$  and  $t \in T$ : if  $(t, p) \in A$ , then  $Post[p, t] = W(p, t)$ , else  $Post[p, t] = 0$

### Incidence Matrix

$$C = Post - Pre$$

### State Equation

- For any enabled transition  $t \in T$ , use vector  $e_t$  as unit vector with 1 at position of  $t$  and 0 otherwise

$$m' = m + C e_t$$

- Note: State equation can be evaluated for any vector  $e_t$  but dynamics is only defined for enabled transitions!

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# Petri Nets: Incidence Matrix and State Equation

## Example

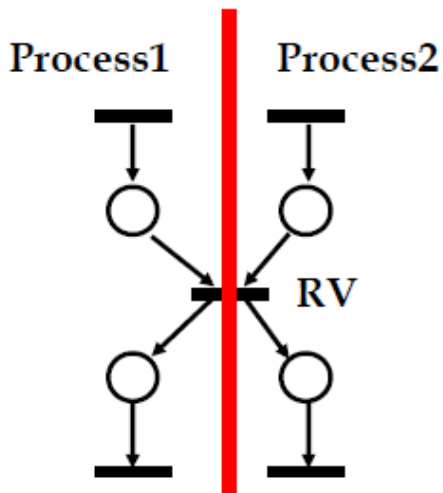
Gap 4

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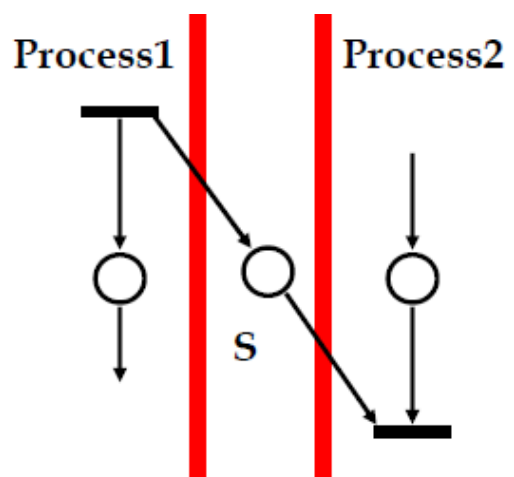
# Petri Nets: Structural Elements

## Rendezvous



→ Processes meet at common transition RV

## Semaphore



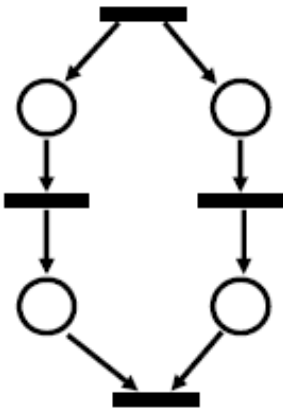
→ Continuation of Process 2 depends on completion of some part of process 1

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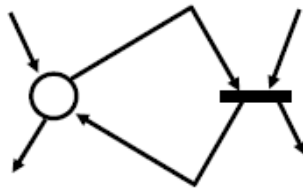
# Petri Nets: Structural Elements

## Fork Join



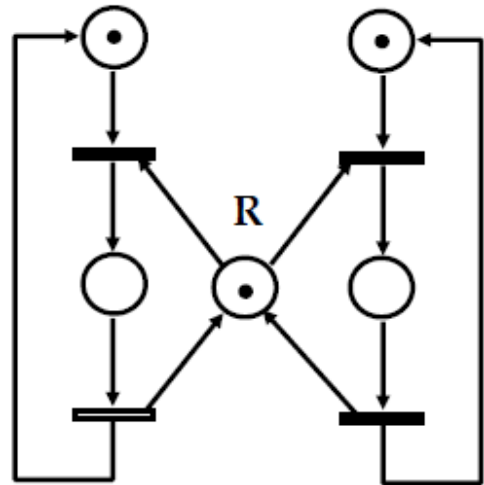
→ Process divides into subprocesses and re-joins

## Guard



→ Transition is only possible if there is token in "guard" place

## Shared Resource



→ Resource R can only be used by one subprocess at a time

# Petri Nets: Structural Elements

## Dining Philosophers Example

- Two philosophers
- Each philosopher either thinks or eats
- There are two forks shared by the philosophers
- Each philosopher can pick any fork if available
- A philosopher thinks if he does not hold any fork
- A philosopher can only eat if he has both forks

Gap 5

# Petri Nets: Structural Elements

## Dining Philosophers Petri Net

Gap 6

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# Petri Nets: Structural Elements

## Dining Philosophers Petri Net

Gap 7

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# PN Languages: Definitions

## Labeled Petri Net

$$N = (P, T, A, W, E, l, x_0, X_m)$$

- $(P, T, A, W)$  is a Petri net graph
- $E$  is the event set for transition labeling
- $l : T \rightarrow E$  is the transition labeling function
- $x_0 \in \mathbb{N}^n$  is the initial state of the net (i.e., the initial number of tokens in each place)
- $X_m \subseteq \mathbb{N}^n$  is the set of marked states of the net.

## Generated Language

$$L(N) = \{l(s) \in E^* \mid s \in T^* \text{ and } s \text{ is enabled from } x_0\}$$

## Marked Language

$$L_m(N) = \{l(s) \in E^* \mid s \in T^* \text{ and } s \text{ is enabled from } x_0 \text{ and } x_0 + C s \in X_m\}$$

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# PN Languages: Example

## Dining Philosophers

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